# Package 'HDCD'

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Maintainer Per August Jarval Moen <pamoen@math.uio.no></pamoen@math.uio.no>
<b>Description</b> Efficient implementations of the following multiple changepoint detection algorithms: Efficient Sparsity Adaptive Change-point estimator by Moen, Glad and Tveten (2023) <doi:10.48550 arxiv.2306.04702="">, Informative Sparse Projection for Estimating Changepoints by Wang and Samworth (2017) <doi:10.1111 rssb.12243="">, and the method of Pilliat et al (2023) <doi:10.1214 23-ejs2126="">.</doi:10.1214></doi:10.1111></doi:10.48550>
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Author Per August Jarval Moen [cre, aut] ( <a href="https://orcid.org/0009-0003-9990-8341">https://orcid.org/0009-0003-9990-8341</a> )
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R topics documented:
ARI       2         CUSUM       3         ESAC       4         ESAC_calibrate       6         ESAC_test       8         ESAC_test_calibrate       10
hausdorff

2 ARI

	Inspect	12
	Inspect_calibrate	14
	Inspect_test	16
	Inspect_test_calibrate	18
	Pilliat	19
	Pilliat_calibrate	22
	Pilliat_test	24
	Pilliat_test_calibrate	
	rescale_variance	
	single_CUSUM	
	single_ESAC	
	single_Inspect	
	single_SBS	
	single_SBS_calibrate	
Index		36
ARI	ARI	

## Description

Computes the Adjusted Rand Index (ARI) of a vector of estimated change-points.

## Usage

```
ARI(etas, eta_hats, n)
```

## Arguments

etas Vector of true change-points
eta\_hats Vector of estimated change-points
n Sample size

## Value

The ARI

```
library(HDCD)
n = 400
true_changepoints = c(50,100)
est_changepoints = c(51,110)
ARI(true_changepoints, est_changepoints,n)
```

CUSUM 3

**CUSUM** 

CUSUM transformation of a matrix

## **Description**

R wrapper for C function computing the CUSUM transformation of a matrix over an interval (s,e]. For compatibility with C indexing, the user should subtract 1 from both s and e when supplying the arguments to the function. If start and stop are not supplied, the CUSUM is computed over the full data, so (s,e]=(0,n]. In this case, CUSUM returns the same result as cusum. transform in the package InspectChangepoint (Wang and Samworth 2020).

## Usage

```
CUSUM(X, start = NULL, stop = NULL)
```

#### **Arguments**

Χ	Matrix of observations, where each row contains a time series
start	Starting point of interval over which the CUSUM should be computed, subtracted by one
stop	Ending point of interval over which the CUSUM should be computed, subtracted by one

#### Value

A matrix of CUSUM values. The (i,j)-th element corresponds to the CUSUM transformation of the i-th row of X, computed over the interval  $(\mathsf{start} + 1, \mathsf{end} + 1]$  and evaluated at position  $\mathsf{start} + 1 + j$ , i.e.  $\sqrt{\frac{e-v}{(e-s)(v-s)}} \sum_{t=s+1}^v X_{i,t} - \sqrt{\frac{v-s}{(e-s)(e-v)}} \sum_{t=v+1}^e X_{i,t}$ , where  $s = (\mathsf{start} + 1)$ ,  $e = (\mathsf{stop} + 1)$  and  $v = \mathsf{start} + 1 + j$ .

#### References

Wang T, Samworth R (2020). *InspectChangepoint: High-Dimensional Changepoint Estimation via Sparse Projection*. R package version 1.1, https://CRAN.R-project.org/package=InspectChangepoint.

```
n = 10
p = 10
set.seed(101)
X = matrix(rnorm(n*p), ncol = n, nrow=p)
# CUSUM over the full data (s,e] = (0,n]
X_cusum = CUSUM(X)

# CUSUM over (s,e] = (3,9]:
s = 3
e = 9
X_cusum = CUSUM(X, start = s-1, stop = e-1)
```

ESAC ESAC

**ESAC** 

Efficient Sparsity Adaptive Change-point estimator

## Description

R wrapper for C function implementing the full ESAC algorithm (see Moen et al. 2023).

## Usage

```
ESAC(
 Χ,
  threshold_d = 1.5,
  threshold_s = 1,
  alpha = 1.5,
 K = 5,
  debug = FALSE,
  empirical = FALSE,
  tol = 0.001,
 N = 1000,
  thresholds = NULL,
  thresholds_test = NULL,
  threshold_d_test = threshold_d,
  threshold_s_test = threshold_s,
  fast = FALSE,
  rescale_variance = TRUE,
  trim = FALSE,
 NOT = TRUE,
 midpoint = FALSE
)
```

## Arguments

X	Matrix of observations, where each row contains a time series
threshold_d	Leading constant for $\lambda(t) \propto r(t)$ for $t=p$ . Only relevant when thresholds=NULL
threshold_s	Leading constant for $\lambda(t) \propto r(t)$ for $t \leq \sqrt{p \log n}$ . Only relevant when thresholds=NULL
alpha	Parameter for generating seeded intervals
K	Parameter for generating seeded intervals
debug	If TRUE, diagnostic prints are provided during execution
empirical	$If  TRUE,  detection  thresholds  are  based  on  Monte  Carlo  simulation  using  ESAC\_calibrate$
tol	If empirical=TRUE, tol is the false error probability tolerance
N	If empirical=TRUE, N is the number of Monte Carlo samples used
thresholds	Vector of manually chosen values of $\lambda(t)$ for $t \in \mathcal{T}$ , decreasing in $t$

ESAC 5

thresholds\_test

Vector of manually chosen values of  $\gamma(t)$  for  $t \in \mathcal{T}$ , decreasing in t

threshold\_d\_test

Leading constant for  $\gamma(t) \propto r(t)$  for t=p. Only relevant when empirical=FALSE

and thresholds\_test=NULL

threshold\_s\_test

Leading constant for  $\gamma(t) \propto r(t)$  for  $t \leq \sqrt{p \log n}$ . Only relevant when

empirical=FALSE and thresholds\_test=NULL

fast If TRUE, ESAC only tests for a change-point at the midpoint of each seeded

interval

rescale\_variance

If TRUE, each row of the data is re-scaled by a MAD estimate using rescale\_variance

trim If TRUE, interval trimming is performed

NOT If TRUE, ESAC uses Narrowest-Over-Threshold selection of change-points

midpoint If TRUE, change-point positions are estimated by the mid-point of the seeded

interval in which the penalized score is the largest

#### Value

A list containing

changepoints vector of estimated change-points

changepointnumber

number of changepoints

CUSUMval the penalized score at the corresponding change-point in changepoints

coordinates a matrix of zeros and ones indicating which time series are affected by a change

in mean, with each row corresponding to the change-point in changepoints

scales vector of estimated noise level for each series

startpoints start point of the seeded interval detecting the corresponding change-point in

changepoints

endpoints end point of the seeded interval detecting the corresponding change-point in

changepoints

thresholds vector of values of  $\lambda(t)$  for  $t \in \mathcal{T}$  in decreasing order

thresholds\_test

vector of values of  $\gamma(t)$  for  $t \in \mathcal{T}$  in decreasing order

## References

Moen PAJ, Glad IK, Tveten M (2023). "Efficient sparsity adaptive changepoint estimation." Arxiv preprint, 2306.04702, https://doi.org/10.48550/arXiv.2306.04702.

6 ESAC\_calibrate

#### **Examples**

```
library(HDCD)
n = 50
p = 50
set.seed(100)
# Generating data
X = matrix(rnorm(n*p), ncol = n, nrow=p)
# Adding a single sparse change-point:
X[1:5, 26:n] = X[1:5, 26:n] +1
# Vanilla ESAC:
res = ESAC(X)
res$changepoints
# Manually setting leading constants for \lambda(t) and \gamma(t)
res = ESAC(X,
           threshold_d = 2, threshold_s = 2, #leading constants for \lambda(t)
           threshold_d_test = 2, threshold_s_test = 2 #leading constants for \gamma(t)
res$changepoints #estimated change-point locations
# Empirical choice of thresholds:
res = ESAC(X, empirical = TRUE, N = 100, tol = 1/100)
res$changepoints
# Manual empirical choice of thresholds (equivalent to the above)
thresholds_emp = ESAC_calibrate(n,p, N=100, tol=1/100)
res = ESAC(X, thresholds_test = thresholds_emp[[1]])
res$changepoints
```

ESAC\_calibrate

Generates empirical penalty function  $\gamma(t)$  for the ESAC algorithm using Monte Carlo simulation

#### **Description**

R wrapper for C function choosing the penalty function  $\gamma(t)$  by Monte Carlo simulation, as described in Appendix B in Moen et al. (2023).

## Usage

```
ESAC_calibrate(
    n,
    p,
    alpha = 1.5,
    K = 5,
    N = 1000,
    tol = 0.001,
    bonferroni = TRUE,
```

7 ESAC\_calibrate

```
fast = FALSE,
rescale_variance = TRUE,
tdf = NULL,
debug = FALSE
```

#### **Arguments**

p

Number of observations n Number time series

alpha Parameter for generating seeded intervals K Parameter for generating seeded intervals Number of Monte Carlo samples used Ν

tol False error probability tolerance

bonferroni If TRUE, a Bonferroni correction applied and the empirical penalty function  $\gamma(t)$ 

is chosen by simulating leading constants of r(t) through Monte Carlo simula-

fast If TRUE, ESAC only tests for a change-point at the midpoint of each seeded

interval

rescale\_variance

If TRUE, each row of the data is re-scaled by a MAD estimate using rescale\_variance

tdf If NULL, samples are drawn from a Gaussian distribution. Otherwise, they are

drawn from a t distribution with tdf degrees of freedom.

debug If TRUE, diagnostic prints are provided during execution

## Value

A list containing

without\_partial

a vector of values of  $\gamma(t)$  for  $t \in \mathcal{T}$  decreasing in t

with\_partial same as without\_partial

vector of threshold values a(t) for  $t \in \mathcal{T}$  decreasing in tas

vector of conditional expectations  $u_{a(t)}$  of a thresholded Gaussian, for  $t \in \mathcal{T}$ nu\_as

decreasing in t

#'

#### References

Moen PAJ, Glad IK, Tveten M (2023). "Efficient sparsity adaptive changepoint estimation." Arxiv preprint, 2306.04702, https://doi.org/10.48550/arXiv.2306.04702.

8 ESAC\_test

#### **Examples**

```
library(HDCD)
n = 50
p = 50

set.seed(100)
thresholds_emp = ESAC_calibrate(n,p, N=100, tol=1/100)
set.seed(100)
thresholds_emp_without_bonferroni = ESAC_calibrate(n,p, N=100, tol=1/100,bonferroni=FALSE)
thresholds_emp[[1]] # vector of \gamma(t) for t = p,...,1
thresholds_emp_without_bonferroni[[1]] # vector of \gamma(t) for t = p,...,1

# Generating data
X = matrix(rnorm(n*p), ncol = n, nrow=p)
# Adding a single sparse change-point:
X[1:5, 26:n] = X[1:5, 26:n] +2

res = ESAC(X, thresholds_test = thresholds_emp[[1]])
res$changepoints
```

ESAC\_test

ESAC single change-point test

## **Description**

R wrapper for C function testing for a single change-point using ESAC (see Moen et al. 2023).

## Usage

```
ESAC_test(
   X,
   threshold_d = 1.5,
   threshold_s = 1,
   debug = FALSE,
   empirical = FALSE,
   thresholds = NULL,
   fast = FALSE,
   tol = 0.001,
   N = 1000,
   rescale_variance = TRUE
)
```

## **Arguments**

X Matrix of observations, where each row contains a time series

threshold\_d Leading constant for  $\gamma(t) \propto r(t)$  for t=p. Only relevant when empirical=FALSE and thresholds=NULL

ESAC\_test 9

Leading constant for  $\gamma(t) \propto r(t)$  for  $t \leq \sqrt{p \log n}$ . Only relevant when threshold\_s empirical=FALSE and thresholds=NULL debug If TRUE, diagnostic prints are provided during execution empirical If TRUE, detection thresholds are based on Monte Carlo simulation using ESAC\_test\_calibrate thresholds Vector of manually chosen values of  $\gamma(t)$  for  $t \in \mathcal{T}$ , decreasing in t fast If TRUE, ESAC only tests for a change-point at the midpoint of each seeded interval tol If empirical=TRUE, tol is the false error probability tolerance If empirical=TRUE, N is the number of Monte Carlo samples used rescale\_variance

If TRUE, each row of the data is re-scaled by a MAD estimate using rescale\_variance

#### Value

1 if a change-point is detected, 0 otherwise

#### References

Moen PAJ, Glad IK, Tveten M (2023). "Efficient sparsity adaptive changepoint estimation." Arxiv preprint, 2306.04702, https://doi.org/10.48550/arXiv.2306.04702.

```
library(HDCD)
n = 50
p = 50
# Generating data
X = matrix(rnorm(n*p), ncol = n, nrow=p)
Y = matrix(rnorm(n*p), ncol = n, nrow=p)
# Adding a single sparse change-point to X (and not Y):
X[1:5, 26:n] = X[1:5, 26:n] +1
# Vanilla ESAC:
resX = ESAC\_test(X)
resY = ESAC\_test(Y)
resY
# Manually setting leading constants for \lambda(t) and \gamma(t)
resX = ESAC_test(X,
                 threshold_d = 2, threshold_s = 2, #leading constants for \gamma(t)
resX
resY = ESAC_test(Y,
                 threshold_d = 2, threshold_s = 2, #leading constants for \gamma(t)
resY
```

10 ESAC\_test\_calibrate

```
# Empirical choice of thresholds:
resX = ESAC_test(X, empirical = TRUE, N = 100, tol = 1/100)
resX
resY = ESAC_test(Y, empirical = TRUE, N = 100, tol = 1/100)
resY

# Manual empirical choice of thresholds (equivalent to the above)
thresholds_test_emp = ESAC_test_calibrate(n,p, N=100, tol=1/100,bonferroni=TRUE)
resX = ESAC_test(X, thresholds = thresholds_test_emp[[1]])
resX
resY = ESAC_test(Y, thresholds = thresholds_test_emp[[1]])
resY
```

ESAC\_test\_calibrate

Generates empirical penalty function  $\gamma(t)$  for single change-point testing using Monte Carlo simulation

## Description

R wrapper for C function choosing the penalty function  $\gamma(t)$  by Monte Carlo simulation, as described in Appendix B in Moen et al. (2023), for testing for a single change-point.

## Usage

```
ESAC_test_calibrate(
    n,
    p,
    bonferroni = TRUE,
    N = 1000,
    tol = 1/1000,
    fast = FALSE,
    rescale_variance = TRUE,
    debug = FALSE
)
```

## **Arguments** n

p	Number time series
bonferroni	If TRUE, a Bonferroni correction applied and the empirical penalty function $\gamma(t)$ is chosen by simulating leading constants of $r(t)$ through Monte Carlo simulation.

N Number of Monte Carlo samples used tol False positive probability tolerance

Number of observations

fast If TRUE, ESAC only tests for a change-point at the midpoint of the interval

 $(0,\ldots,n]$ 

ESAC\_test\_calibrate 11

```
rescale_variance
```

If TRUE, each row of the data is re-scaled by a MAD estimate using rescale\_variance

debug If TRUE, diagnostic prints are provided during execution

#### Value

A list containing a vector of values of  $\gamma(t)$  for  $t \in \mathcal{T}$  decreasing (element #1), a vector of corresponding values of the threshold a(t) (element #3), a vector of corresponding values of  $\nu_{a(t)}$ 

A list containing

```
without_partial
```

a vector of values of  $\gamma(t)$  for  $t \in \mathcal{T}$  decreasing in t

with\_partial same as without\_partial

as vector of threshold values a(t) for  $t \in \mathcal{T}$  decreasing in t

nu\_as vector of conditional expectations  $\nu_{a(t)}$  of a thresholded Gaussian, for  $t \in \mathcal{T}$ 

decreasing in t

#### References

Moen PAJ, Glad IK, Tveten M (2023). "Efficient sparsity adaptive changepoint estimation." Arxiv preprint, 2306.04702, https://doi.org/10.48550/arXiv.2306.04702.

```
library(HDCD)
n = 50
p = 50
set.seed(100)
thresholds_emp = ESAC_test_calibrate(n,p, bonferroni=TRUE,N=100, tol=1/100)
set.seed(100)
thresholds_emp_without_bonferroni = ESAC_test_calibrate(n,p, bonferroni=FALSE,N=100, tol=1/100)
thresholds_emp[[1]] # vector of \gamma(t) for t = p, ..., 1
thresholds_emp_without_bonferroni[[1]] # vector of \gamma for t = p,...,1
# Generating data
X = matrix(rnorm(n*p), ncol = n, nrow=p)
Y = matrix(rnorm(n*p), ncol = n, nrow=p)
# Adding a single sparse change-point to X (and not Y):
X[1:5, 26:n] = X[1:5, 26:n] +2
resX = ESAC_test(X, thresholds = thresholds_emp[[1]])
resY = ESAC_test(Y, thresholds = thresholds_emp[[1]])
resY
```

12 Inspect

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Hausdorff distance between two sets

## **Description**

Computes the Hausdorff distance between two sets represented as vectors v1 and v2. If v1 == NULL and v2 != NULL, then the largest distance between an element of v1 and the set  $\{1, n\}$  is returned, and vice versa. If both vectors are NULL,  $\emptyset$  is returned.

## Usage

```
hausdorff(v1, v2, n)
```

#### **Arguments**

v1	Vector representing set 1
v2	Vector representing set 2
n	Sample size (only relevant when either v1 or v2 is NULL)

#### Value

The Hausdorff distance between v1 and v2

## **Examples**

```
library(HDCD)
n = 400
true_changepoints = c(50,100)
est_changepoints = c(51,110)
hausdorff(true_changepoints, est_changepoints,n)
hausdorff(true_changepoints, NULL,n)
hausdorff(NULL, est_changepoints,n)
hausdorff(NULL,NULL)
```

Inspect

*Informative sparse projection for estimating change-points (Inspect)* 

## **Description**

R wrapper for C function implementing a Narrowest-Over-Threshold variant of Inspect Wang and Samworth (2018) as specified in Appendix C in Moen et al. (2023). Note that the algorithm is only implemented for  $\mathcal{S} = \mathcal{S}_2$ , in the notation of Moen et al. (2023).

Inspect 13

## Usage

```
Inspect(
   X,
   lambda = NULL,
   xi = NULL,
   alpha = 1.5,
   K = 5,
   eps = 1e-10,
   empirical = FALSE,
   maxiter = 10000,
   N = 100,
   tol = 1/100,
   rescale_variance = TRUE,
   debug = FALSE
)
```

## Arguments

Χ	Matrix of observations, where each row contains a time series
lambda	Manually specified value of $\lambda$ (can be NULL, in which case $\lambda \leftarrow \sqrt{\log(p\log n)/2}$ )
xi	Manually specified value of $\xi$ (can be NULL, in which case $\xi \leftarrow 4\sqrt{\log(np)}$ )
alpha	Parameter for generating seeded intervals
K	Parameter for generating seeded intervals
eps	Threshold for declaring numerical convergence of the power method
empirical	If TRUE, the detection threshold $xi$ is based on Monte Carlo simulation using Inspect_calibrate
maxiter	Maximum number of iterations for the power method
N	If empirical=TRUE, N is the number of Monte Carlo samples used
tol	If empirical=TRUE, tol is the false error probability tolerance
rescale_variand	ce
	If TRUE, each row of the data is re-scaled by a MAD estimate using ${\tt rescale\_variance}$

#### Value

debug

A list containing

changepoints vector of estimated change-points

changepointnumber

number of changepoints

CUSUMval vector with the sparse projected CUSUMs corresponding to changepoints

If TRUE, diagnostic prints are provided during execution

coordinates a matrix of zeros and ones indicating which time series are affected by a change

in mean, with each row corresponding to the change-point in changepoints

scales vector of estimated noise level for each series

14 Inspect\_calibrate

## References

Moen PAJ, Glad IK, Tveten M (2023). "Efficient sparsity adaptive changepoint estimation." Arxiv preprint, 2306.04702, https://doi.org/10.48550/arXiv.2306.04702.

Wang T, Samworth RJ (2018). "High dimensional change point estimation via sparse projection." *Journal of the Royal Statistical Society: Series B (Statistical Methodology)*, **80**(1), 57–83. ISSN 1467-9868, doi:10.1111/rssb.12243, https://rss.onlinelibrary.wiley.com/doi/abs/10.1111/rssb.12243.

#### **Examples**

```
library(HDCD)
n = 50
p = 50
set.seed(100)
# Generating data
X = matrix(rnorm(n*p), ncol = n, nrow=p)
# Adding a single sparse change-point:
X[1:5, 26:n] = X[1:5, 26:n] +1
# Vanilla Inspect:
res = Inspect(X)
res$changepoints
# Manually setting leading constants for \lambda(t) and \gamma(t)
res = Inspect(X,
              lambda = sqrt(log(p*log(n))/2),
              xi = 4*sqrt(log(n*p))
)
res$changepoints #estimated change-point locations
# Empirical choice of thresholds:
res = Inspect(X, empirical=TRUE, N = 100, tol = 1/100)
res$changepoints
# Manual empirical choice of thresholds (equivalent to the above)
thresholds_emp = Inspect_calibrate(n,p, N=100, tol=1/100)
res = Inspect(X, xi = thresholds_emp$max_value)
res$changepoints
```

Inspect\_calibrate

Generates empirical detection threshold  $\xi$  using Monte Carlo simulation

## **Description**

R wrapper for C function choosing empirical detection threshold  $\xi$  for the Narrowest-Over-Threshold variant of Inspect (as specified in section 4.2 in Moen et al. 2023) using Monte Carlo simulation.

Inspect\_calibrate 15

## Usage

```
Inspect_calibrate(
    n,
    p,
    N = 100,
    tol = 1/100,
    lambda = NULL,
    alpha = 1.5,
    K = 5,
    eps = 1e-10,
    maxiter = 10000,
    rescale_variance = TRUE,
    debug = FALSE
)
```

## Arguments

n	Number of observations
p	Number time series
N	Number of Monte Carlo samples used
tol	False positive probability tolerance
lambda	Manually specified value of $\lambda$ (can be NULL, in which case $\lambda \leftarrow \sqrt{\log(p\log n)/2}$ )
alpha	Parameter for generating seeded intervals
K	Parameter for generating seeded intervals
eps	Threshold for declaring numerical convergence of the power method
maxiter	Maximum number of iterations for the power method
rescale_variand	ce
	If TRUE, each row of the data is re-scaled by a MAD estimate using ${\tt rescale\_variance}$
debug	If TRUE, diagnostic prints are provided during execution

## Value

A list containing

max\_value the empirical threshold

## References

Moen PAJ, Glad IK, Tveten M (2023). "Efficient sparsity adaptive changepoint estimation." Arxiv preprint, 2306.04702, https://doi.org/10.48550/arXiv.2306.04702.

```
library(HDCD)
n = 50
p = 50
```

16 Inspect\_test

```
set.seed(100)
thresholds_emp = Inspect_calibrate(n,p, N=100, tol=1/100)
thresholds_emp$max_value # xi

# Generating data
X = matrix(rnorm(n*p), ncol = n, nrow=p)
# Adding a single sparse change-point:
X[1:5, 26:n] = X[1:5, 26:n] +2

res = Inspect(X, xi = thresholds_emp$max_value)
res$changepoints
```

Inspect\_test

Inspect single change-point test

## Description

R wrapper for C function testing for a single change-point using Inspect Wang and Samworth (2018).

## Usage

```
Inspect_test(
   X,
   lambda = NULL,
   xi = NULL,
   eps = 1e-10,
   empirical = FALSE,
   N = 100,
   tol = 1/100,
   maxiter = 10000,
   rescale_variance = TRUE,
   debug = FALSE
)
```

## Arguments

X	Matrix of observations, where each row contains a time series
lambda	Manually specified value of $\lambda$ (can be NULL, in which case $\lambda \leftarrow \sqrt{\log(p\log n)/2})$
xi	Manually specified value of $\xi$ (can be NULL, in which case $\xi \leftarrow 4\sqrt{\log(np)}$ )
eps	Threshold for declaring numerical convergence of the power method
empirical	If TRUE, the detection threshold $xi$ is based on Monte Carlo simulation using <code>Inspect_test_calibrate</code>
N	If empirical=TRUE, N is the number of Monte Carlo samples used
tol	If empirical=TRUE, tol is the false error probability tolerance

Inspect\_test 17

#### Value

1 if a change-point is detected, 0 otherwise

#### References

Wang T, Samworth RJ (2018). "High dimensional change point estimation via sparse projection." *Journal of the Royal Statistical Society: Series B (Statistical Methodology)*, **80**(1), 57–83. ISSN 1467-9868, doi:10.1111/rssb.12243, https://rss.onlinelibrary.wiley.com/doi/abs/10.1111/rssb.12243.

```
library(HDCD)
n = 50
p = 50
# Generating data
X = matrix(rnorm(n*p), ncol = n, nrow=p)
Y = matrix(rnorm(n*p), ncol = n, nrow=p)
# Adding a single sparse change-point to X (and not Y):
X[1:5, 26:n] = X[1:5, 26:n] +1
# Vanilla Inspect:
resX = Inspect_test(X)
resY = Inspect_test(Y)
resY
# Manually setting \lambda and \xi:
resX = Inspect_test(X,
                    lambda = sqrt(log(p*log(n))/2),
                    xi = 4*sqrt(log(n*p))
)
resX
resY = Inspect_test(Y,
                    lambda = sqrt(log(p*log(n))/2),
                    xi = 4*sqrt(log(n*p))
)
resY
# Empirical choice of thresholds:
resX = Inspect_test(X, empirical = TRUE, N = 100, tol = 1/100)
resY = Inspect_test(Y, empirical = TRUE, N = 100, tol = 1/100)
```

```
resY

# Manual empirical choice of thresholds (equivalent to the above)
thresholds_test_emp = Inspect_test_calibrate(n,p, N=100, tol=1/100)
resX = Inspect_test(X, xi = thresholds_test_emp$max_value)
resX
resY = Inspect_test(Y, xi = thresholds_test_emp$max_value)
resY
```

Inspect\_test\_calibrate

Generates empirical detection threshold  $\xi$  for single change-point testing using Monte Carlo simulation

## Description

R wrapper for C function choosing the empirical detection threshold  $\xi$  for Inspect Wang and Samworth (2018) for single change-point testing using Monte Carlo simulation.

## Usage

```
Inspect_test_calibrate(
   n,
   p,
   N = 100,
   tol = 1/100,
   lambda = NULL,
   eps = 1e-10,
   maxiter = 10000,
   rescale_variance = TRUE,
   debug = FALSE
)
```

## **Arguments**

n	Number of observations	
p	Number time series	
N	Number of Monte Carlo samples used	
tol	False positive probability tolerance	
lambda	Manually specified value of $\lambda$ (can be NULL, in which case $\lambda \leftarrow \sqrt{\log(p\log n)/2}$ )	
eps	Threshold for declaring numerical convergence of the power method	
maxiter	Maximum number of iterations for the power method	
rescale_variand	ale_variance	
	If TRUE, each row of the data is re-scaled by a MAD estimate using ${\tt rescale\_variance}$	
debug	If TRUE, diagnostic prints are provided during execution	

Pilliat 19

#### Value

A list containing

max\_value the empirical threshold

#### References

Wang T, Samworth RJ (2018). "High dimensional change point estimation via sparse projection." *Journal of the Royal Statistical Society: Series B (Statistical Methodology)*, **80**(1), 57–83. ISSN 1467-9868, doi:10.1111/rssb.12243, https://rss.onlinelibrary.wiley.com/doi/abs/10.1111/rssb.12243.

## **Examples**

```
library(HDCD)
n = 50
p = 50

set.seed(100)
thresholds_emp = Inspect_test_calibrate(n,p,N=100, tol=1/100)
thresholds_emp

# Generating data
X = matrix(rnorm(n*p), ncol = n, nrow=p)
Y = matrix(rnorm(n*p), ncol = n, nrow=p)

# Adding a single sparse change-point to X (and not Y):
X[1:5, 26:n] = X[1:5, 26:n] +2
resX = Inspect_test(X, xi = thresholds_emp$max_value)
resX
resY = Inspect_test(Y, xi = thresholds_emp$max_value)
resY
```

Pilliat

Pilliat multiple change-point detection algorithm

## **Description**

R wrapper function for C implementation of the multiple change-point detection algorithm by Pilliat et al. (2023), using seeded intervals generated by Algorithm 4 in Moen et al. (2023). For the sake of simplicity, detection thresholds are chosen independently of the width of the interval in which a change-point is tested for (so r=1 is set for all intervals).

20 Pilliat

```
Usage
```

```
Pilliat(
 Χ,
  threshold_d_const = 4,
  threshold_bj_const = 6,
  threshold_partial_const = 4,
 K = 2,
  alpha = 1.5,
  empirical = FALSE,
  threshold_dense = NULL,
  thresholds_partial = NULL,
  thresholds_bj = NULL,
  N = 100,
  tol = 0.01,
  rescale_variance = TRUE,
  test_all = FALSE,
  debug = FALSE
)
```

#### **Arguments**

X Matrix of observations, where each row contains a time series

threshold\_d\_const

Leading constant for the analytical detection threshold for the dense statistic

threshold\_bj\_const

Leading constant for  $p_0$  when computing the detection threshold for the Berk-

Jones statistic

threshold\_partial\_const

Leading constant for the analytical detection threshold for the partial sum statis-

tic

K Parameter for generating seeded intervals alpha Parameter for generating seeded intervals

empirical If TRUE, detection thresholds are based on Monte Carlo simulation using Pilliat\_calibrate

threshold\_dense

Manually specified value of detection threshold for the dense statistic

thresholds\_partial

Vector of manually specified detection thresholds for the partial sum statistic,

for sparsities/partial sums  $t = 1, 2, 4, \dots, 2^{\lfloor \log_2(p) \rfloor}$ 

thresholds\_bj Vector of manually specified detection thresholds for the Berk-Jones statistic,

order corresponding to  $x = 1, 2, \dots, x_0$ 

N If empirical=TRUE, N is the number of Monte Carlo samples used

tol If empirical=TRUE, tol is the false error probability tolerance

rescale\_variance

If TRUE, each row of the data is re-scaled by a MAD estimate (see rescale\_variance)

test\_all If TRUE, the algorithm tests for a change-point in all candidate positions of each

considered interval

debug If TRUE, diagnostic prints are provided during execution

Pilliat 21

#### Value

A list containing

changepoints vector of estimated change-points

number\_of\_changepoints

number of changepoints

scales vector of estimated noise level for each series

startpoints start point of the seeded interval detecting the corresponding change-point in

changepoints

endpoints end point of the seeded interval detecting the corresponding change-point in

changepoints

#### References

Moen PAJ, Glad IK, Tveten M (2023). "Efficient sparsity adaptive changepoint estimation." Arxiv preprint, 2306.04702, https://doi.org/10.48550/arXiv.2306.04702.

Pilliat E, Carpentier A, Verzelen N (2023). "Optimal multiple change-point detection for high-dimensional data." *Electronic Journal of Statistics*, **17**(1), 1240 – 1315.

```
library(HDCD)
n = 50
p = 50
set.seed(100)
# Generating data
X = matrix(rnorm(n*p), ncol = n, nrow=p)
# Adding a single sparse change-point:
X[1:5, 26:n] = X[1:5, 26:n] +2
# Vanilla Pilliat:
res = Pilliat(X)
res$changepoints
# Manually setting leading constants for detection thresholds
res = Pilliat(X, threshold_d_const = 4, threshold_bj_const = 6, threshold_partial_const=4)
res$changepoints #estimated change-point locations
# Empirical choice of thresholds:
res = Pilliat(X, empirical = TRUE, N = 100, tol = 1/100)
res$changepoints
# Manual empirical choice of thresholds (equivalent to the above)
thresholds_emp = Pilliat_calibrate(n,p, N=100, tol=1/100)
thresholds_emp$thresholds_partial # thresholds for partial sum statistic
thresholds_emp$thresholds_bj # thresholds for Berk-Jones statistic
thresholds_emp$threshold_dense # thresholds for Berk-Jones statistic
res = Pilliat(X, threshold_dense =thresholds_emp$threshold_dense,
              thresholds_bj = thresholds_emp$thresholds_bj,
```

Pilliat\_calibrate

```
thresholds\_partial \ = thresholds\_emp\$thresholds\_partial \ ) \\ res\$changepoints
```

Pilliat\_calibrate

Generates detection thresholds for the Pilliat algorithm using Monte Carlo simulation

## **Description**

R wrapper for function choosing detection thresholds for the Dense, Partial sum and Berk-Jones statistics in the multiple change-point detection algorithm of Pilliat et al. (2023) using Monte Carlo simulation. When Bonferroni==TRUE, the detection thresholds are chosen by simulating the leading constant in the theoretical detection thresholds given in Pilliat et al. (2023), similarly as described in Appendix B in Moen et al. (2023) for ESAC. When Bonferroni==TRUE, the thresholds for the Berk-Jones statistic are theoretical and not chosen by Monte Carlo simulation.

## Usage

```
Pilliat_calibrate(
   n,
   p,
   N = 100,
   tol = 0.01,
   bonferroni = TRUE,
   threshold_bj_const = 6,
   K = 2,
   alpha = 1.5,
   rescale_variance = TRUE,
   test_all = FALSE,
   debug = FALSE
)
```

#### **Arguments**

n	Number of observations	
р	Number time series	
N	Number of Monte Carlo samples used	
tol	False error probability tolerance	
bonferroni	If TRUE, a Bonferroni correction applied and the detection thresholds for each statistic is chosen by simulating the leading constant in the theoretical detection thresholds	
threshold_bj_const		

Leading constant for  $p_0$  for the Berk-Jones statistic

K Parameter for generating seeded intervals alpha Parameter for generating seeded intervals

Pilliat\_calibrate 23

```
rescale_variance
```

If TRUE, each row of the data is re-scaled by a MAD estimate (see rescale\_variance)

test\_all If TRUE, a change-point test is applied to each candidate change-point position

in each interval. If FALSE, only the mid-point of each interval is considered

debug If TRUE, diagnostic prints are provided during execution

#### Value

```
A list containing
```

thresholds\_partial

vector of thresholds for the Partial Sum statistic (respectively for  $t = 1, 2, 4, \dots, 2^{\lfloor \log_2(p) \rfloor}$  number of terms in the partial sum)

threshold\_dense

threshold for the dense statistic

thresholds\_bj vector of thresholds for the Berk-Jones static (respectively for  $x = 1, 2, \dots, x_0$ )

#### References

Moen PAJ, Glad IK, Tveten M (2023). "Efficient sparsity adaptive changepoint estimation." Arxiv preprint, 2306.04702, https://doi.org/10.48550/arXiv.2306.04702.

Pilliat E, Carpentier A, Verzelen N (2023). "Optimal multiple change-point detection for high-dimensional data." *Electronic Journal of Statistics*, **17**(1), 1240 – 1315.

```
library(HDCD)
n = 50
p = 50
set.seed(100)
thresholds_emp = Pilliat_calibrate(n,p, N=100, tol=1/100)
thresholds_emp$thresholds_partial # thresholds for partial sum statistic
thresholds_emp$thresholds_bj # thresholds for Berk-Jones statistic
thresholds_emp$threshold_dense # thresholds for Berk-Jones statistic
set.seed(100)
thresholds_emp_without_bonferroni = Pilliat_calibrate(n,p, N=100, tol=1/100,bonferroni = FALSE)
thresholds_emp_without_bonferroni$thresholds_partial # thresholds for partial sum statistic
thresholds_emp_without_bonferroni$thresholds_bj # thresholds for Berk-Jones statistic
thresholds_emp_without_bonferroni$threshold_dense # thresholds for Berk-Jones statistic
# Generating data
X = matrix(rnorm(n*p), ncol = n, nrow=p)
# Adding a single sparse change-point:
X[1:5, 26:n] = X[1:5, 26:n] +2
res = Pilliat(X, threshold_dense =thresholds_emp$threshold_dense,
              thresholds_bj = thresholds_emp$thresholds_bj,
              thresholds_partial =thresholds_emp$thresholds_partial )
res$changepoints
```

24 Pilliat\_test

Pilliat\_test

Pilliat single change-point test

## **Description**

R wrapper function testing for a single change-point using the three test statistics in the multiple change point detection algorithm of Pilliat et al. (2023). See also Appendix E in Moen et al. (2023).

#### Usage

```
Pilliat_test(
   X,
   empirical = FALSE,
   N = 100,
   tol = 0.05,
   thresholds_partial = NULL,
   threshold_dense = NULL,
   threshold_d_const = 4,
   threshold_bj_const = 6,
   threshold_partial_const = 4,
   rescale_variance = TRUE,
   fast = FALSE,
   debug = FALSE
)
```

#### **Arguments**

Matrix of observations, where each row contains a time series
 empirical If TRUE, detection thresholds are based on Monte Carlo simulation
 N If empirical=TRUE, N is the number of Monte Carlo samples used

tol If empirical=TRUE, tol is the false error probability tolerance

thresholds\_partial

Vector of manually specified detection thresholds for the partial sum statistic, for sparsities/partial sums  $t=1,2,4,\ldots,2^{\lfloor \log_2(p) \rfloor}$ 

threshold\_dense

Manually specified value of detection threshold for the dense statistic

thresholds\_bj Vector of manually specified detection thresholds for the Berk-Jones statistic, order corresponding to  $x=1,2,\ldots,x_0$ 

threshold\_d\_const

Leading constant for the analytical detection threshold for the dense statistic threshold\_bj\_const

Leading constant for  $p_0$  when computing the detection threshold for the Berk-Jones statistic

Pilliat\_test 25

```
threshold_partial_const
```

Leading constant for the analytical detection threshold for the partial sum statis-

rescale\_variance

If TRUE, each row of the data is re-scaled by a MAD estimate (see rescale\_variance)

fast If TRUE, only the mid-point of (0, ..., n] is tested for a change-point. Otherwise

a test is performed at each candidate change-point poisition

debug If TRUE, diagnostic prints are provided during execution

#### Value

1 if a change-point is detected, 0 otherwise

#### References

Moen PAJ, Glad IK, Tveten M (2023). "Efficient sparsity adaptive changepoint estimation." Arxiv preprint, 2306.04702, https://doi.org/10.48550/arXiv.2306.04702.

Pilliat E, Carpentier A, Verzelen N (2023). "Optimal multiple change-point detection for high-dimensional data." *Electronic Journal of Statistics*, **17**(1), 1240 – 1315.

```
library(HDCD)
n = 200
p = 200
# Generating data
X = matrix(rnorm(n*p), ncol = n, nrow=p)
Y = matrix(rnorm(n*p), ncol = n, nrow=p)
# Adding a single sparse change-point to X (and not Y):
X[1:5, 100:200] = X[1:5, 100:200] +1
# Vanilla Pilliat test:
resX = Pilliat_test(X)
resX
resY = Pilliat_test(Y)
# Manually setting leading constants for the theoretical thresholds for the three
# test statistics used
resX = Pilliat_test(X,
                    threshold_d_const=4,
                    threshold_bj_const=6,
                    threshold_partial_const=4
)
resX
resY = Pilliat_test(Y,
                    threshold_d_const=4,
                    threshold_bj_const=6,
```

26 Pilliat\_test\_calibrate

```
threshold_partial_const=4
)
resY
# Empirical choice of thresholds:
resX = Pilliat_test(X, empirical = TRUE, N = 100, tol = 1/100)
resY = Pilliat_test(Y, empirical = TRUE, N = 100, tol = 1/100)
resY
# Manual empirical choice of thresholds (equivalent to the above)
thresholds_test_emp = Pilliat_test_calibrate(n,p, N=100, tol=1/100,bonferroni=TRUE)
resX = Pilliat_test(X,
                    threshold_dense=thresholds_test_emp$threshold_dense,
                    thresholds_bj = thresholds_test_emp$thresholds_bj,
                    thresholds_partial = thresholds_test_emp$thresholds_partial
)
resX
resY = Pilliat_test(Y,
                    threshold_dense=thresholds_test_emp$threshold_dense,
                    thresholds_bj = thresholds_test_emp$thresholds_bj,
                    thresholds_partial = thresholds_test_emp$thresholds_partial
)
resY
```

Pilliat\_test\_calibrate

Generates detection thresholds for the Pilliat algorithm for testing for a single change-point using Monte Carlo simulation

## **Description**

R wrapper for function choosing detection thresholds for the Dense, Partial sum and Berk-Jones statistics in the multiple change-point detection algorithm of Pilliat et al. (2023) for single change-point testing using Monte Carlo simulation. When Bonferroni==TRUE, the detection thresholds are chosen by simulating the leading constant in the theoretical detection thresholds given in Pilliat et al. (2023), similarly as described in Appendix B in Moen et al. (2023) for ESAC. When Bonferroni==TRUE, the thresholds for the Berk-Jones statistic are theoretical and not chosen by Monte Carlo simulation.

## Usage

```
Pilliat_test_calibrate(
   n,
   p,
   N = 100,
   tol = 1/100,
   threshold_bj_const = 6,
   bonferroni = TRUE,
```

27 Pilliat\_test\_calibrate

```
rescale_variance = TRUE,
  fast = FALSE,
  debug = FALSE
)
```

#### **Arguments**

р

n Number of observations

Number time series Ν Number of Monte Carlo samples used

False error probability tolerance tol

threshold\_bj\_const

Leading constant for  $p_0$  for the Berk-Jones statistic

bonferroni If TRUE, a Bonferroni correction applied and the detection thresholds for each

statistic is chosen by simulating the leading constant in the theoretical detection

thresholds

rescale\_variance

If TRUE, each row of the data is rescaled by a MAD estimate

If FALSE, a change-point test is applied to each candidate change-point position fast

in each interval. If FALSE, only the mid-point of each interval is considered

If TRUE, diagnostic prints are provided during execution debug

#### Value

A list containing

thresholds\_partial

vector of thresholds for the Partial Sum statistic (respectively for  $t=1,2,4,\ldots,2^{\lfloor \log_2(p) \rfloor}$ 

number of terms in the partial sum)

threshold\_dense

threshold for the dense statistic

thresholds\_bj vector of thresholds for the Berk-Jones static (respectively for  $x = 1, 2, \dots, x_0$ )

```
library(HDCD)
n = 50
p = 50
set.seed(100)
thresholds_test_emp = Pilliat_test_calibrate(n,p, bonferroni=TRUE,N=100, tol=1/100)
set.seed(100)
thresholds_test_emp_without_bonferroni = Pilliat_test_calibrate(n,p,
                                         bonferroni=FALSE,N=100, tol=1/100)
thresholds_test_emp # thresholds with bonferroni correction
thresholds_test_emp_without_bonferroni # thresholds without bonferroni correction
# Generating data
```

28 rescale\_variance

```
X = matrix(rnorm(n*p), ncol = n, nrow=p)
Y = matrix(rnorm(n*p), ncol = n, nrow=p)
# Adding a single sparse change-point to X (and not Y):
X[1:5, 25:50] = X[1:5, 25:50] +2
resX = Pilliat_test(X,
                    threshold_dense=thresholds_test_emp$threshold_dense,
                    thresholds_bj = thresholds_test_emp$thresholds_bj,
                    thresholds_partial = thresholds_test_emp$thresholds_partial
)
resX
resY = Pilliat_test(Y,
                    threshold_dense=thresholds_test_emp$threshold_dense,
                    thresholds_bj = thresholds_test_emp$thresholds_bj,
                    thresholds_partial = thresholds_test_emp$thresholds_partial
)
resY
```

rescale\_variance

Re-scales each row of matrix by its MAD estimate

## Description

R wrapper for C function computing the (rescaled) median absolute difference in differences for each row of the input matrix. The rescaling factor is set to 1.05 (corresponding to the Normal distribution). Each row of the input matrix then re-scaled by the corresponding noise estimate.

#### Usage

```
rescale_variance(X, debug = FALSE)
```

## **Arguments**

X A  $p \times n$  matrix

debug If TRUE, diagnostic prints are provided during execution

## Value

A list containing

X the input matrix, variance re-scaled and flattened

scales vector of MAD estimates of the noise level of each row of the input matrix

single\_CUSUM 29

#### **Examples**

```
library(HDCD)
n = 200
p = 500
set.seed(101)
# Generating data
X = matrix(rnorm(n*p), ncol = n, nrow=p)

ret = rescale_variance(X)
ret$X #rescaled matrix
ret$scales #estimated noise level for each time series (each row)

# Note that the rescaled matrix is in (column wise) vector form. To transform it back to a matrix,
# do the following:
rescaled_X = matrix(ret$X, nrow = p, ncol=n)
```

single\_CUSUM

CUSUM transformation of matrix at a specific position

## Description

R wrapper for C function computing the CUSUM transformation of matrix over an interval (s, e] evaluated at a specific position. For compatibility with C indexing, the user should subtract 1 from s, e and v when supplying the arguments to the function. If start and stop are not supplied, the CUSUM is computed over the full data, so (s, e] = (0, n].

#### Usage

```
single_CUSUM(X, start = NULL, stop = NULL, pos)
```

## **Arguments**

X	Matrix of observations, where each row contains a time series
start	Starting point of interval over which the CUSUM should be computed, subtracted by one
stop	Ending point of interval over which the CUSUM should be computed, subtracted by one
pos	Position at which the CUSUM should be evaluated, subtracted by one

## Value

A vector of CUSUM values, each corresponding to a row of the input matrix. The i-th element corresponds to the CUSUM transformation of the i-th row of X, computed over the interval (start + 1, end+1] and evaluated at position pos, i.e.  $\sqrt{\frac{e-v}{(e-s)(v-s)}} \sum_{t=s+1}^{v} X_{i,t} - \sqrt{\frac{v-s}{(e-s)(e-v)}} \sum_{t=v+1}^{e} X_{i,t}$ , where s = (start + 1), e = (stop + 1) and v = pos + 1.

30 single\_ESAC

#### **Examples**

```
n = 10
p = 10
set.seed(101)
X = matrix(rnorm(n*p), ncol = n, nrow=p)
# CUSUM over the full data (s,e] = (0,n] evaluated at position v=4
position = 4
X_cusum_single = single_CUSUM(X,pos = position-1)
X_cusum_single
# verifying that this corresponds to the 4-th row of output of CUSUM():
X_cusum = CUSUM(X)
X_cusum[,4]
```

single\_ESAC

Efficient Sparsity Adaptive Change-point estimator for a single change-point

## **Description**

R wrapper for C function implementing ESAC for single change-point estimation, as described in section 3.1 in Moen et al. (2023)

#### Usage

```
single_ESAC(
   X,
   threshold_d = 1.5,
   threshold_s = 1,
   rescale_variance = FALSE,
   debug = FALSE
)
```

#### **Arguments**

X Matrix of observations, where each row contains a time series threshold\_d Leading constant for  $\lambda(t) \propto r(t)$  for t=p

threshold\_s Leading constant for  $\lambda(t) \propto r(t)$  for  $t \leq \sqrt{p \log n}$ .

rescale\_variance

If TRUE, each row of the data is re-scaled by a MAD estimate using rescale\_variance

debug If TRUE, diagnostic prints are provided during execution

## Value

A list containing

pos estimated change-point location

s the value of  $t \in \mathcal{T}$  at which the sparsity specific score is maximized

31 single\_Inspect

#### References

Moen PAJ, Glad IK, Tveten M (2023). "Efficient sparsity adaptive changepoint estimation." Arxiv preprint, 2306.04702, https://doi.org/10.48550/arXiv.2306.04702.

#### **Examples**

```
library(HDCD)
n = 500
p = 500
set.seed(101)
# Generating data
X = matrix(rnorm(n*p), ncol = n, nrow=p)
# Adding a single sparse change-point:
X[1:5, 201:500] = X[1:5, 201:500] +1
 res = single_ESAC(X,rescale_variance=TRUE)
 res$pos
# Manually setting the leading constants for \lambda(t):
# here \label{eq:here} \labe
                                                                                                 = 2 (t \log (ep \log n^4 / t^2) + \log(n^4))
 res = single_ESAC(X, threshold_d = 2, threshold_s = 2)
 res$pos
```

single\_Inspect

Inspect for single change-point estimation

## Description

R wrapper for C function for single change-point estimation using Inspect (Wang and Samworth 2018). Note that the algorithm is only implemented for  $S = S_2$ , in the notation of Wang and Samworth (2018).

#### Usage

```
single_Inspect(
  Χ,
  lambda = sqrt(log(p * log(n))/2),
  eps = 1e-10,
  rescale_variance = FALSE,
 maxiter = 10000,
  debug = FALSE
)
```

## **Arguments**

Χ Matrix of observations, where each row contains a time series Manually specified value of  $\lambda$  (can be NULL, in which case  $\lambda \leftarrow \sqrt{\log(p \log n)/2}$ )

lambda

32 single\_SBS

eps Threshold for declaring numerical convergence of the power method rescale\_variance

If TRUE, each row of the data is re-scaled by a MAD estimate using rescale\_variance

maxiter Maximum number of iterations for the power method debug If TRUE, diagnostic prints are provided during execution

#### Value

A list containing

pos estimated change-point location

CUSUMval projected CUSUM value at the estimated change-point position

#### References

Wang T, Samworth RJ (2018). "High dimensional change point estimation via sparse projection." *Journal of the Royal Statistical Society: Series B (Statistical Methodology)*, **80**(1), 57–83. ISSN 1467-9868, doi:10.1111/rssb.12243, https://rss.onlinelibrary.wiley.com/doi/abs/10.1111/rssb.12243.

## **Examples**

```
library(HDCD)
n = 500
p = 500
set.seed(101)
# Generating data
X = matrix(rnorm(n*p), ncol = n, nrow=p)
# Adding a single sparse change-point:
X[1:5, 201:500] = X[1:5, 201:500] +1

res = single_Inspect(X,rescale_variance=TRUE)
res$pos
# Manually setting the value of \lambda:
res = single_Inspect(X, lambda = 2*sqrt(log(p*log(n))/2))
res$pos
```

single\_SBS

Sparsified Binary Segmentation for single change-point estimation

## **Description**

R wrapper for C function for single change-point estimation using Sparsified Binary Segmentation Cho and Fryzlewicz (2015).

single\_SBS 33

#### Usage

```
single_SBS(
   X,
   threshold = NULL,
   rescale_variance = TRUE,
   empirical = FALSE,
   N = 100,
   tol = 1/100,
   debug = FALSE
)
```

#### **Arguments**

X Matrix of observations, where each row contains a time series

threshold Manually specified value of the threshold  $\pi_T$ 

rescale\_variance

If TRUE, each row of the data is re-scaled by a MAD estimate using rescale\_variance

empirical If TRUE, the threshold is based on Monte Carlo simulation

N If empirical=TRUE, N is the number of Monte Carlo samples used tol If empirical=TRUE, tol is the false error probability tolerance

debug If TRUE, diagnostic prints are provided during execution

#### Value

A list containing

pos estimated change-point location

maxval maximum thresholded and aggregated CUSUM at the estimated change-point

position

## References

Cho H, Fryzlewicz P (2015). "Multiple-change-point detection for high dimensional time series via sparsified binary segmentation." *Journal of the Royal Statistical Society. Series B (Statistical Methodology)*, **77**(2), 475–507. ISSN 1369-7412, Publisher: [Royal Statistical Society, Wiley], https://www.jstor.org/stable/24774746.

```
# Single SBS
library(HDCD)
n = 50
p = 50
set.seed(101)
# Generating data
X = matrix(rnorm(n*p), ncol = n, nrow=p)
# Adding a single sparse change-point:
X[1:5, 26:n] = X[1:5, 26:n] +1
```

```
res = single_SBS(X,threshold=7,rescale_variance=TRUE)
res$pos

# Choose threhsold by Monte Carlo:
res = single_SBS(X,empirical=TRUE,rescale_variance=TRUE)
res$pos
```

single\_SBS\_calibrate Generates threshold  $\pi_T$  for Sparsified Binary Segmentation for single change-point detection

## **Description**

R wrapper for function choosing empirical threshold  $\pi_T$  using Monte Carlo simulation for single change-point Sparsified Binary Segmentation. More specifically, the function returns the empirical upper tol quantile of CUSUMs over p time series, each of length n, based on N number of runs.

## Usage

```
single_SBS_calibrate(
   n,
   p,
   N = 100,
   tol = 1/100,
   rescale_variance = TRUE,
   debug = FALSE
)
```

## Arguments

n	Number of observations	
p	Number time series	
N	Number of Monte Carlo samples used	
tol	False positive probability tolerance	
rescale_variance		
	If TRUE, each row of the data is rescaled by a MAD estimate	
debug	If TRUE, diagnostic prints are provided during execution	

#### Value

Threshold

single\_SBS\_calibrate 35

```
library(HDCD)
n = 50
p = 50
set.seed(101)

# Simulate threshold
pi_T_squared = single_SBS_calibrate(n=n,p=p,N=100, tol=1/100, rescale_variance = TRUE)
pi_T_squared

# Generating data
X = matrix(rnorm(n*p), ncol = n, nrow=p)
# Adding a single sparse change-point:
X[1:5, 26:n] = X[1:5, 26:n] +1

# Run SBS
res = single_SBS(X, threshold=sqrt(pi_T_squared), rescale_variance=TRUE)
res$pos
```

## **Index**

```
ARI, 2
CUSUM, 3
ESAC, 4
ESAC_calibrate, 4, 6
ESAC_test, 8
ESAC_test_calibrate, 9, 10
hausdorff, 12
Inspect, 12
Inspect_calibrate, 13, 14
Inspect_test, 16
Inspect_test_calibrate, 16, 18
Pilliat, 19
Pilliat_calibrate, 20, 22
Pilliat_test, 24
Pilliat_test_calibrate, 26
rescale_variance, 5, 7, 9, 11, 13, 15, 17, 18,
        20, 23, 25, 28, 30, 32, 33
single_CUSUM, 29
single\_ESAC, 30
single_Inspect, 31
single_SBS, 32
single\_SBS\_calibrate, 34
```